# Signatures, trees and pdes





A rough path between mathematics and data science



Terry Lyons CIRM - 12 March 2021

with many others ... but particularly Cris, Patrick, James, James, Varun, Cris, Maud, Peter, Roly, Sam,... Tom, Harald, Hao, Patricia

### A DataSig vision



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We channel our research around developing the mathematics needed to model and understand complex streams of nonstationary multimodal data. We build prototypes that have real world value to develop this understanding. This is only possible because of significant collaboration and partnership.



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# Modelling behavior of evolving systems

### A public domain collaboration on detecting malware



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### DataSig: an EPSRC/UKRI 5-year program grant



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### Mathematics

- rough path theory and signatures
- describing the interactions between complex systems from the top down
- extending the calculus of differential equations to complex contexts

#### Data science

- the notion of an unparameterized path captured by the order of events
- clean and minimal universal feature sets (expected) signature
- the notion of a neural controlled differential equation
- the notion of a pde-kernel
- a principled mathematical framework that allows further innovation (e.g. simulation)

### **Embedded contexts**

• streamed data is everywhere; Chinese handwriting, hospital wards, event logs ...



### Streamed data

- a character drawn on the screen of an iPhone
- an order book
- a piece of text
- progression through hospital record
- astronomical data
- video of a person moving
- an evolving stream of emotions
- ICU data to detect sepsis
- the evolving stock position in a supermarket or computer switch

Ensembles of streamed data

- the event log of processes generated by malware
- the behaviour of crowds
- the evolution of cancer cell lines

#### **Key questions**

- understand what you have observed
- predict the distribution of what is happening next
- identify anomalies



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# Some maths of evolving systems

### Data science does not like symmetry



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- Re-parameterisation is a huge symmetry group
- Multimodal streams modulo reparameterisation form a group
- Representing this group in the tensor algebra provides a faithful feature set and removes the symmetry
- Drawn from old mathematics, new tools, signature and log signature, and new maths describing the functions on streams



### Different sampling procedures



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- The letter "3" is drawn from top to bottom
- The x coordinate of the evolving symbol sampled differently (at uneven speeds)



### Different sampling procedures



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The number "3" x, y coordinates – same picture drawn at two different speeds

- no consistent wavelets
- reparameterisations do not form a linear space!



### Different sampling procedures



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- The letter "3" is drawn from top to bottom
- How does one describe the three or any path modulo the symmetry of parametrisation?



The signature of a path describes an unparameterised stream  $\gamma$ 



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Signature is a *top down* description for unparameterised paths that describes a path segment through its effects of stylised nonlinear systems

$$dS = S \otimes d\gamma$$

It filters out the infinite dimensional noise of resampling allowing prediction and classification with *much* smaller learning sets.

It gives fixed dimensional feature sets regardless of the sample points.\*

\* missing data/varying parameterisation not issues although inadequacy of sampling may be

The signature - faithful and universal features describing an unparameterised stream



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The signature of a stream  $\gamma$  over I = [s, t] defined by  $\sum_{k=0}^{\infty} S_k$ where  $S_0 = 1$  and

$$S_k(\gamma, I) \coloneqq \iint_{s < u_1 < \dots < u_k < t} d\gamma_{u_1} d\gamma_{u_2} \dots d\gamma_{u_k}$$

These "Fourier-like" features exactly describe the *unparameterised* stream (Hambly Lyons Annals Math 2010) up to appropriate null sets. Projected controlled differential equations are universal models

 $< e, Y_t >$  where  $dY_u = f(Y_u)dX_u$ 

# Analysis, geometry, combinatorial Hopf/dendriform/sensor algebras



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- Signature leads to linear space of real valued sensors  $\langle e | S_I \rangle$  on streams
- Pointwise multiplication and integration of these functionals
- can usefully be described in purely algebraic language.
- The log signature is structurally important.



## Analysis, geometry, combinatorial Hopf/dendriform/sensor algebras



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- The *Signature* is a faithful embedding of the *unparametrized* stream into a vector space
- Continuous functions on streams can be well approximated by linear functionals on signatures
- The Expected Signature describes the ensemble of paths
- The log-signature describes paths without redundancy
- There is a natural pde kernel



## Analysis, geometry, combinatorial Hopf/dendriform/sensor algebras



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- Let be x, y be unparametrized paths in H and consider the bilinear form K(x, y) ≔ (S(x), S(y)). Franz J. Kiraly, Harald Oberhauser; JMLR 20(31):1-45, 2019 gave a kernel trick for the tangent kernel for the truncated signature embedding.
- Salvi et al. then identified the Goursat pde as the kernel trick for the untrucated kernel and gave analytic sense for it even for rough paths:



$$\frac{\partial^2 K(x|_{[u_0,u]},y|_{[v_0,v]})}{\partial u \partial v} = \langle \dot{x}, \dot{y} \rangle K(x|_{[u_0,u]},y|_{[v_0,v]})$$

### Recovering the curves from the signature



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Weixin Yang, Jaiwei Chang

#### Fermanian<sup>17</sup>

### Our data



5

Ô

10

time

15 20

5

Ó.

10

time

15

Fig. 1. Visual representation of selected channels of one single streaming tree. Each plot represents the evolution in time of the value of a given channel of the streaming tree, on its various branches. A red dot indicates a point where the currently-tracked process sets off a child process, causing the tree to branch.

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time

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### Paths or Signatures? Long/short vessel



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- The vectorisation of unparametrized streams allows efficient use of many standard methods.
- For example, anomaly detection can be successfully applied this to these real-world shipping trajectories example.

Vessel length 14.8m Vessel length 18.3m Vessel length 19.1m Vessel length 22.9m Vessel length 23.1m Stream length: 114.0km Stream length: 788.4km Stream length: 382.6km Stream length: 415.1km Stream length: 85.9km Number of points: 1571 Number of points: 1559 Number of points: 1536 Number of points: 1580 Number of points: 1580





### Neural Controlled differential equations



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### Use controlled differential equations to model policies



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Train a neural f so that  $dy = f(y)d\gamma, y_0 = a$ Where a represents the current state and  $\gamma$  determines the

policy. Allows learning counterfactuals.

Neural Rough Differential Equations for Long Time Series <u>https://arxiv.org/abs/2009.08295</u>

James Morrill, Cristopher Salvi, Patrick Kidger, James Foster, Terry Lyons

### **Ensembles of paths**



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### Process tree example: Expected signatures of clouds of paths



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Developed a way to apply expected signature techniques by viewing processes as trees evolving over time (eg the crop yield prediction task).

Predicting the yield of wheat crops over a region from the longitudinal measurements of climatic variables recorded across different locations of the region.

Eurostat dataset containing the total annual regional yield of wheat crops in mainland France - divided in 22 administrative regions - from 2015 to 2017.

#### for i in tqdm(range(NUM\_TRIALS)):

pwES = pathwiseExpectedSignatureTransform(order=2). SpwES = SignatureTransform(order=3).fit\_transform(p X\_train, X\_test, y\_train, y\_test = train\_test\_split model = GridSearchCV(pipe, parameters, verbose=0, n model.fit(X\_train, y\_train) y\_pred = model.predict(X\_test) usetest[i] = mean\_squared\_error(y\_pred, y\_test)

### Process tree example: Expected signatures of clouds of paths



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Viewing a cloud of interacting paths evolving over time as an expected signature, it can be merged with other channels, and the process repeated. PDE kernels can manage dimension. The crop yield prediction task matches this model: AISTATS 2021 arxiv.org/pdf/2006.05805.pdf

The climatic measurements (temperature, soil humidity and precipitation) are extracted from the GLDAS database (Rodell et al, 2004), are recorded every 6 hours at a spatial resolution of 0.25° × 0.25°, and their number varies across regions. Add regional policy information, etc.

Model	MSE	ΜΑΡΕ
Baseline	2.38	23.31
DeepSets	2.67	22.88
DR-RBF	.82	13.18
DR-Matern32	.82	13.18
DR-GA	.72	12.55
KES	.65	12.34
SES	.62	10.98

### Process tree example: Expected signatures of clouds of paths

0.00

0.25

**Developed SK-tree structure to apply** standardised expected signature techniques to host-based event logs, by viewing processes as trees evolving over time analysed as expected signatures through a PDE kernel. 2102.07904.pdf (arxiv.org)

We demonstrate the SK-Tree to detect malicious events on a portion of the publicly available DARPA OpTC dataset, achieving an initial AUROC score of 98% for a supervised question.



## Communication



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### Landmark-based action recognition

To communicate our methodology, and aside from our papers, with their software we are constructing notebooks with introductory examples of what we can do.

People moving can easily be anonymized to landmarks. It is a static process. The moving stick people still contain information.

Peter Foster has put together a simple notebook you can run that demonstrates viable approaches to recognizing these actions that can be trained on small datasets.

https://www.datasig.ac.uk/examples

#### mank you:

 $dy = f(y)d\gamma$ 

full[indices] = Paral
 delayed(mmd\_distanc
 for i in range(N)
 for j in range(i,N)

indices = np.tril\_indic
K\_full[indices] = K\_ful
return K full

class TreeKernel(BaseEstima
 def \_\_init\_\_(self, K\_fu
 super(TreeKernel, s
 self.K\_full = K\_ful
 self.sigma = sigma

def transform(self, ind return np.exp(-self